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| --- | --- |
| Localization\_pose | header {  timestamp\_sec: 1551784841.93  module\_name: "localization"  sequence\_num: 9813  }  pose {  position {  x: 552873.141037  y: 4182766.70679  z: 10.1238040924  }  orientation {  qx: -0.000323303422192  qy: 0.000815817154944  qz: 0.920587062836  qw: 0.390536427498  }  linear\_velocity {  x: -6.19401931763  y: 0.139211624861  z: 0.00012568384409  }  linear\_acceleration {  x: 1.10996984434  y: -1.27253139942  z: -9.75978325506  }  angular\_velocity {  x: -0.0043677779987  y: 0.00567089976961  z: -0.0024595711077  }  heading: -2.37322587092  linear\_acceleration\_vrf {  x: -1.67436599731  y: 0.0740453600883  z: -9.76195441931  }  angular\_velocity\_vrf {  x: 0.00711610494182  y: -0.000803495408036  z: -0.0024498004932  }  euler\_angles {  x: 2.16947784683e-05  y: -6.28168967593  z: 4.73462104918  }  }  measurement\_time: 1551784841.11 |
| Pointcloud(map) | -확인해보기 |
| radar | header {  timestamp\_sec: 1551784844.04  module\_name: "conti\_radar"  sequence\_num: 1385  }  contiobs {  header {  timestamp\_sec: 1551784844.04  module\_name: "conti\_radar"  sequence\_num: 1385  }  clusterortrack: false  obstacle\_id: 1  longitude\_dist: 2.25722789764  lateral\_dist: 11.9336528778  longitude\_vel: 0.00212007388473  lateral\_vel: -3.61930597137e-06  rcs: 11.0  dynprop: 1  longitude\_dist\_rms: 0.0  lateral\_dist\_rms: 0.0  longitude\_vel\_rms: 0.0  lateral\_vel\_rms: 0.0  probexist: 1.0  meas\_state: 2  longitude\_accel: 0.0  lateral\_accel: 0.0  oritation\_angle: 0.857055664062  longitude\_accel\_rms: 0.0  lateral\_accel\_rms: 0.0  oritation\_angle\_rms: 0.0  length: 3.74075317383  width: 10.6000061035  obstacle\_class: 1  } |
| Velodyne64 => 16 | is\_dense: Trueheader:  seq: 1022  stamp:  secs: 1551784842  nsecs: 719524096  frame\_id: velodyne  height: 1  width: 10961  fields:  -  name: x  offset: 0  datatype: 7  count: 1  -  name: y  offset: 4  datatype: 7  count: 1  -  name: z  offset: 8  datatype: 7  count: 1  -  name: intensity  offset: 16  datatype: 2  count: 1  -  name: timestamp  offset: 24  datatype: 8  count: 1  is\_bigendian: False  point\_step: 32  row\_step: 350752  data:[개많음] |
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